

System Monitor is a software package for configuring and tuning automotive control systems. It has built-in support for motor sport systems and can be tailored to support third party control units.

System Monitor not only allows you to tune data for your program versions, but also manages those versions on disk, allowing them to be located quickly for programming or modification.

Familiar controls and extensive use of menus and accelerator keys make System Monitor easy to set up and to use, both at the track and at the test bed.

System Monitor supports configuration of logging for the ATLAS display and analysis software and both applications can run on the same PC.

Programming/Tuning

- Programming of unit with program and data • versions
- Tuning of unit by modification of editable • parameters including 1 and 2D maps
- Live tuning with verification; integrity checks to • ensure synchronisation between System Monitor and the unit
- On-track tuning when linked by a suitable RF data • connection to the unit
- Display of measurement parameters for live • feedback
- Data Wizard to compare and merge data versions •
- Management of program and data versions stored • on disk
- Can be used with PUMA for automated tuning

Diagnostics

- Monitoring of unit errors and events •
- Virtual parameters derived from measurements by • user defined mathematical functions
- User definable alarms triggered by measurement • conditions
- Configuration and uploading of engine and chassis • history reports
- Enter a message and send it directly to the unit •
- Read and display an area of memory on the unit

Configuration

- Configuration of parameter data to be logged in • memory on the unit
- Configuration of parameter data to be transmitted over • telemetry
- Programming of sensor and actuator calibration data
- Configuration of CAN transmit and receive messages
- Configuration of analogue and digital signals from MESL units.

Extendibility

- ActiveX interface provides functions for communication with unit, allowing creation of both custom measurement displays and unit commands
- Extensive on-line help with context sensitive links to the application

Scalability

- Supports multiple application programs on the same control unit
- Supports multiple control units •

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What you need

- An ASAP2 file for each application program which will run on the unit. This describes the editable (configurable) and measurement parameters
- A hex file for each application, containing the • program code and base data
- A link between the PC and the control unit. This can be either Ethernet, HDLC or CAN

Getting started

- Create a program version and data version for • each application; these are more compact and faster to open and compare than the ASAP2 and hex files
- Create a project, linking together a program and • data version for each application plus the screen layouts and other configurations you will make
- In the Parameter Explorer, find the editable and • measurement parameters for all applications

Monitoring

- Program the unit with each of the program and data versions you have created
- Create windows displaying measurement parameters

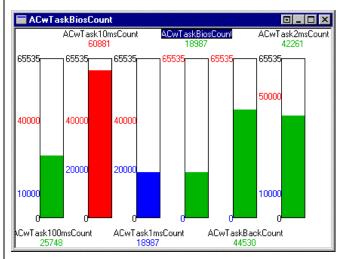
📰 Brakes			
Description	Value		Units
Achieved Balance	48.57		%
Measured brake balance	33.10	۸	%
Brake Steer Current	0.655	8	A
Brake balance Moog current	1.30	8	mA
Brake balance error	-3.96	Ŧ	%
Brake balance current demand	5.84	Ŧ	mA
Brake balance demand	49.34		%
Front brake wear	-100.00		mm
Rear brake wear	-40.65		mm
Front Brake Fluid Level	1.50	8	mm
Rear Brake Fluid Level	0.43	8	mm

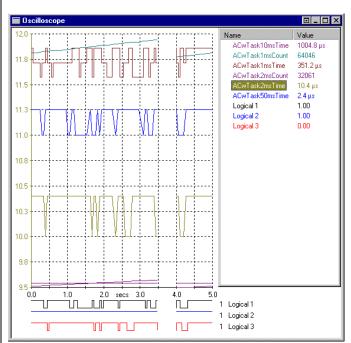
- Create custom displays with the grid window, showing measurement values or freeform text in any cell
- Display bar and dial graphs for visual feedback.

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Show changes over time with the oscilloscope window

System Monitor requests and receives on-line data from the unit, allowing you to observe the behaviour of each application as it runs



•

Create windows for diagnostics showing errors, events and areas of memory

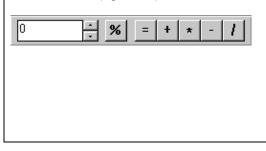
Events- (1003 Events)						
ļ	Date	Time	Event	Description		
¢	11/07/2000	16:23:59	E-1F11:Differential Integral Current Reset	0004 0004 0001		
•	11/07/2000	16:24:02	E-1202:Shifts Disallowed	0000 0000 0001		
•	11/07/2000	16:28:37	E-1201:Shifts Allowed	0000 0106 0001		
•	11/07/2000	16:28:37	E-1F31:Differential Control Initialising	0106 0000 0000		
•	11/07/2000	16:28:37	E-1F35:Differential Control Stopped - pHydraulic Low	0000 0000 0000		
•	11/07/2000	16:28:37	E-1F11:Differential Integral Current Reset	0004 0004 0001		
•	11/07/2000	16:28:40	E-1202:Shifts Disallowed	0000 0000 0001		
۰	11/07/2000	16:33:38	E-0046:Burst Logging memory wrapped	0000 0000 0000		
۰	11/07/2000	16:43:15	E-0041:SM Link Lost	0A64 0B0F 0003		
٠	11/07/2000	16:51:07	E-0046:Burst Logging memory wrapped	0000 0000 0000		
•	11/07/2000	16:59:50	E-3003:Pedal spare - voltage out of range	0000 0000 0000		
۰	11/07/2000	17:02:35	E-0041:SM Link Lost	0A64 0B0F 0003		
۰	11/07/2000	17:08:35	E-0046:Burst Logging memory wrapped	0000 0000 0000		
•	11/07/2000	17:12:07	E-3003:Pedal spare - voltage out of range	0000 0000 0000	-	

Tuning

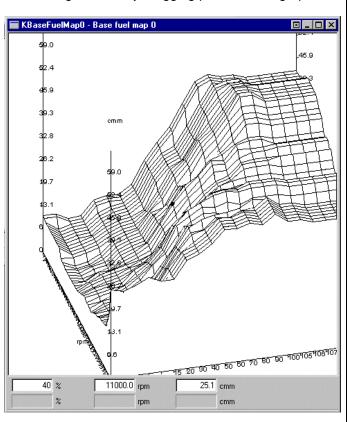
Create windows showing scalar, 1-axis map, 2-axis • map, array and string parameters

awFX_EngBrkCylCut [rpm]	10000	11000	11500	13000	14000	15000	16000
awFM_EngBrkCylCut1 []	4	5	7	7	9	9	10
awFM_EngBrkCylCut2[]	4	5	6	7	8	9	9
awFM_EngBrkCylCut3 []	4	5	E	7	8	7	9
awFM_EngBrkCylCut4 []	4	5	6	7	7	8	9
awFM_EngBrkCylCut5 []	4	3	6	6	7	8	9
awFM_EngBrkCylCut6 []	4	5	5	6	7	8	9
•							
 11500 rpm	F	5			m		

Change values by simply typing or by using the maths bar (eg +10%)



1 and 2 axis maps can be viewed as Graphs. Change values by dragging points on the graph.



- Send changes to the unit as they are made or download all changes later
- Make adjustments easily using the rotary controls on the VE-81 Adjustment board, connected via the serial port
- System Monitor detects when the contents of its edit buffer differ from the contents of the live tune RAM on the unit

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Version Management

- Save your tuned data versions to directories reserved for each application
- Compare your tuned data with the base version or with • tuned data from earlier program versions

r:\testdata\0011\000.dtv	
Parameters	Descriptions
🖃 👘 🤄 engine	
📄 🚔 Scalar	
🚽 🔀 📕 🖉 🖉 BlipDemandOverride_AC	Blip demand override AC (-1 = From
🚽 🔀 📕 🖉 🖉 BlipDemandOverride_EC	Blip demand override EC (-1 = From
🚽 🚅 🔋 KPT1000_Setup_initial	PT1000 analog input config bit field
f DilDefVal	Oil pressure Default Value
f DilMin	Oil pressure Minimum
📄 🔄 1-Axis Map	
? 🔲 KDecelModeSel	Decel mode select
KFCylinderCut	Rev Limit Spark Cut Patterns
KFPLSLCut	Pit Limiter Spark Cut Patterns
🦳 ? 🔲 KidleMap	Idle map select
🦳 ? 🔲 KignMap	Ignition map select
📉 🔀 🚺 TOilMap	Oil temperature (PT1000) Map
📉 🔀 🚺 TWaterMap	Water temperature Map
🗄 💼 2-Axis Map	
<u></u>	
Select and merge para versions	ameters from earlier data

Print reports for easy reference •

Compare 0025003 with 0025000 Compare different values, different sizes, different data types, different definitions for d:helpdemolengine\025503.dtv d:helpdemolengine\025503.dtv

KFIgnBase Base Ignition Map [°CA] CommonAxis Throttle [%] 2.5 5.0 7.5 10.0 15.0 20.0 25.0 30.0 35.0 40.0 45.0 50.0 55.0 60.0 65.0 70.0 800 23.8 24.4 35.5 30.0 28.8 25.1 28.0 28.8 30.8 34.5 31.4 33.9 35.4 38.6 37.1 35.6 38 1500 17.4 24.4 35.5 30.0 28.8 25.1 28.0 28.8 30.8 34.5 31.4 33.9 35.4 38.6 37.1 35.6 38 2000 14.8 20.1 35.5 30.0 28.8 20.0 24.0 28.8 30.8 34.5 31.4 33.9 35.4 38.6 37.1 2500 10.5 18.2 24.7 22.5 17.1 16.5 19.3 23.5 30.8 34.5 31.4 33.9 35.4 38.6 37.1 35.6 3000 4.9 13.2 15.3 13.6 12.0 13.6 15.9 18.8 30.8 30.8 31.4 33.9 35.4 35.0 37.1 35.6 38 3500 4 1 14 2 17 7 15 4 15 0 15 8 17 1 18 5 31 9 31 8 33 2 38 2 39 3 40 4 38 8 37 1 34 6000 16.1 32.9 39.4 40.9 41.3 40.7 41.7 35.1 43.1 42.8 43.0 41.4 42.4 43.3 46.4 51.0 4 $\begin{array}{c} \mathsf{5000} \ \ \mathsf{16}, \ \ \mathsf{15}, \ \mathsf{25}, \ \mathsf{3}, \ \mathsf{34}, \ \mathsf{40}, \ \mathsf{9}, \ \mathsf{1,3} \ \mathsf{40}, \ \mathsf{9}, \ \mathsf{1,3} \ \mathsf{40}, \ \mathsf{1,3} \ \mathsf{41}, \ \mathsf{13}, \ \mathsf{13}, \ \mathsf{14}, \ \mathsf{14}, \ \mathsf{42}, \ \mathsf{4}, \ \mathsf{43}, \ \mathsf{3}, \ \mathsf{40}, \ \mathsf{4}, \ \mathsf{11}, \ \mathsf{4}, \ \mathsf{4}, \ \mathsf{41}, \ \mathsf{3}, \ \mathsf{40}, \ \mathsf{4}, \ \mathsf{11}, \ \mathsf{11}, \ \mathsf{4}, \ \mathsf{41}, \ \mathsf{41}, \ \mathsf{3}, \ \mathsf{41}, \ \mathsf{$ 6500 7500 16.6 37.3 37.6 38.0 37.3 34.8 34.0 33.1 44.7 43.1 41.5 38.3 36.0 34.0 34.4 35 8000 17.5 39.9 39.2 39.3 40.6 39.4 39.0 37.9 49.2 48.3 42.6 41.3 41

Custom Commands

Write your own commands and interfaces to help in your development process

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